

## EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	0	((haptic adj interface adj device) with (sensor) and (sensor adj signal) with (movement) and (position adj housing) with (actuator adj housing) and actuator with (output adj rotary adj force) with (haptic adj feedback adj signal) with (processor) and (haptic adj feedback adj signal) with (sensor adj signal) and (flexure) with (plurality adj flex\$4 adj joint\$1) and (flexure) with (coupled adj5 actuator) and (housing) and (flexure) with (translat\$3) with (rotary adj force) with (linear adj motion) and (flexure) with (output adj haptic adj feedback) with (rotary adj force) and (flexure) with (first adj flex adj joint) and (second adj flex adj joint) and (movable adj actuator adj portion) with (housing adj5 flexure) with (flex adj joint) and (flexure adj mechanism) with (actuator adj housing) with (interface adj device) with (flex adj joint)).clm.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/05/06 23:52